**Mission Challenges for Infrastructure:** 

Launch & Transfer to L2 point

•On-orbit Assembly vs. Self-Deployment

Astronaut EVA vs. Robotic Operations

Servicing & Refueling

Technology





Phase 1: Launch  $\rightarrow$  L2

## **Option 1: Completely Automated**

•Launch to LEO or GTO

•Low thrust spiral to Earth-Sun L2, with or without transfer vehicle

•Telescope self-deploys en route to L2

- No systems checkout before reaching L2
- •Transfer vehicle (if used) returns to LEO

### **Technology Requirements**

•Basic launch vehicle and packaging technology



•No additional infrastructure

Cons

Pros

- •No guarantee system works
- Conservative thinking
- Packaging for launch
- •Fuel concerns if no transfer vehicle is used

## Phase 1: Launch $\rightarrow$ L2

### **Option 2: Assembled**

- Launch to LEO
- •Transfer to Earth-Moon L1 Gateway via Hybrid Propellant Module
- •Partially or completely assembled at L1, either by EVA or robotically, pre-placement system verification
  - •Transfer to Earth-Sun L2, transfer vehicle returns to L1 or LEO

### **Technology Requirements**

•Tools for assembly (station, robots, launch and transfer vehicles, etc.)





#### Pros

•Handle unforeseen issues

Revolutionary thinking

•Simplifies packaging, servicing if telescope is assembly-designed

#### Cons

- •Requires new infrastructure
- •Greater human interaction

•Meeting technology requirements

## Phase 1: Launch $\rightarrow$ L2

### **Option 3: Partially Automated**

- •Launch to LEO or GTO
- •Transfer to L2 (possibly low thrust spiral) with piggybacking autonomous robot
- •Telescope deploys or is partially constructed by robot (or human EVA, in alternate situation) at L2
  - Robot performs systems checkout at L2
- •Robot and transfer vehicle return to LEO Technology Requirements
- Autonomous robot or human-rated vehicle capable of reaching L2
  Launch and packaging technology



#### Pros

•Minimal additional infrastructure

•System verification possible

•Simplifies packaging etc.

#### Cons

- •Meeting technology requirements
- •Uncharted territory for space operations
- Launching robot w/ system

## **Phase 2: Servicing**

### **Option 1: Completely Automated**

•Repair vehicle (autonomous vehicle such as ASTRO or human rated vehicle) transfers to L2 (NEP?)

•On-site repair, refueling, and partreplacement (robotically or human EVA)

•Repair vehicle returns, either to L1 Gateway or LEO

#### **Technology Requirements**

•Autonomous robots or human-rated vehicle capable of operating at L2



#### Pros

•1 round trip—minimizes time requirement

Revolutionary approach

L2

Cons

- Technology needs
- •Distance from supporting infrastructure in case of error
- •Uncharted territory for servicing operations

## **Phase 2: Servicing**

### **Option 2: Partially Automated**

•Transfer vehicle intercepts telescope at L2, ferries back to L1 (LEO not a good option)

•Repair, refueling, and part replacement at station (L1 Gateway, other vehicle) using robots or humans

•Transfer vehicle ferries telescope back to L2, returns to L1 or LEO

Technology Requirements

Servicing technology at L1



Pros

•Reliable servicing method

•Greater range of options at base station

Cons

•Transfer time—2 round trips

Additional infrastructure

•Must potentially transfer both sections of telescope both directions